

FIG. 1

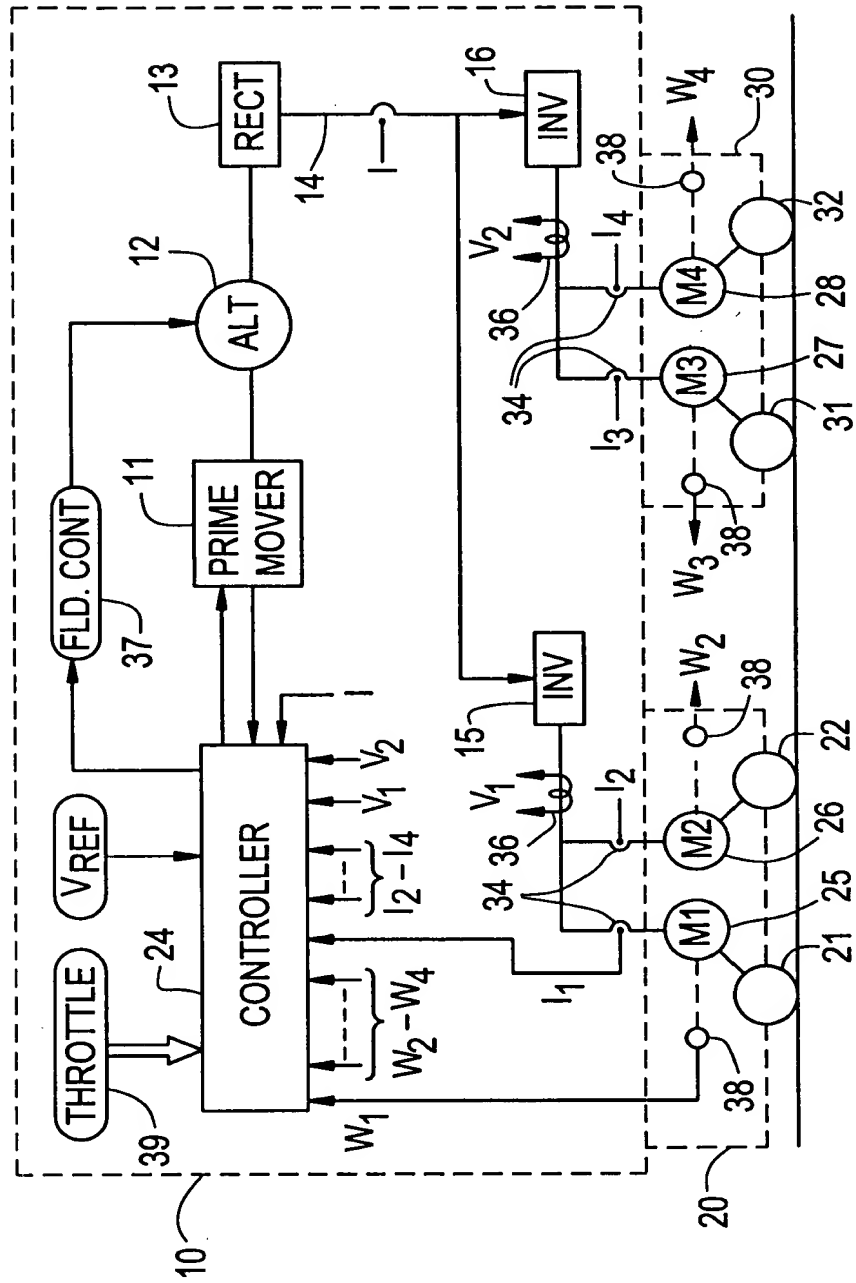
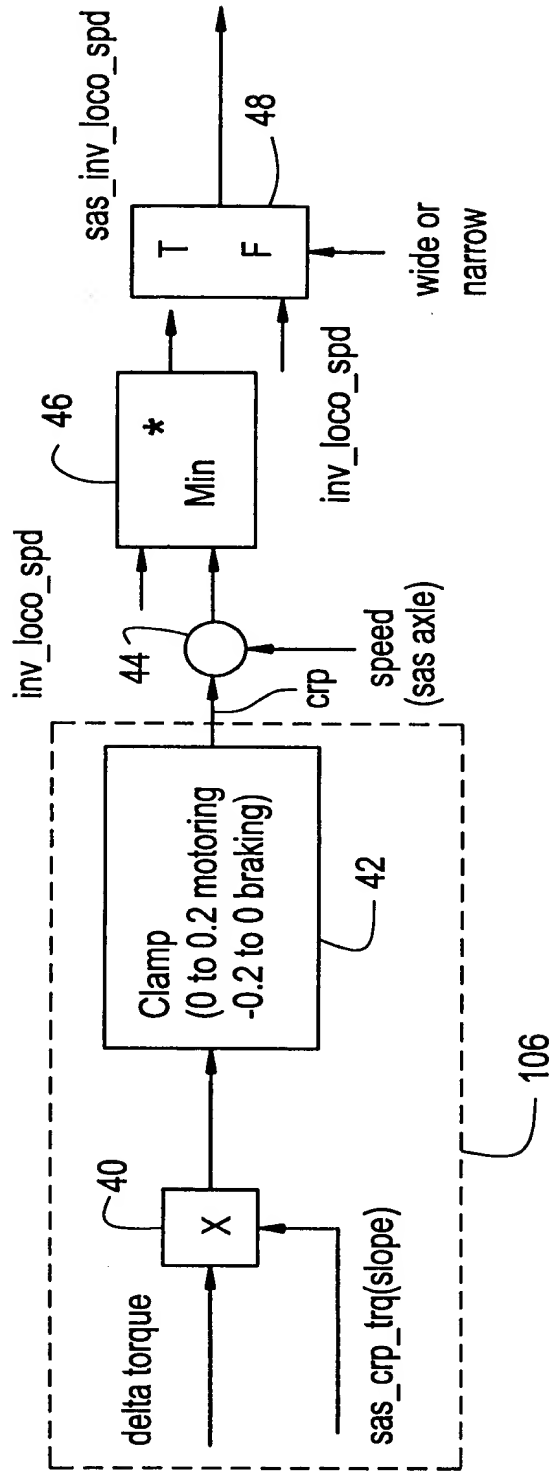
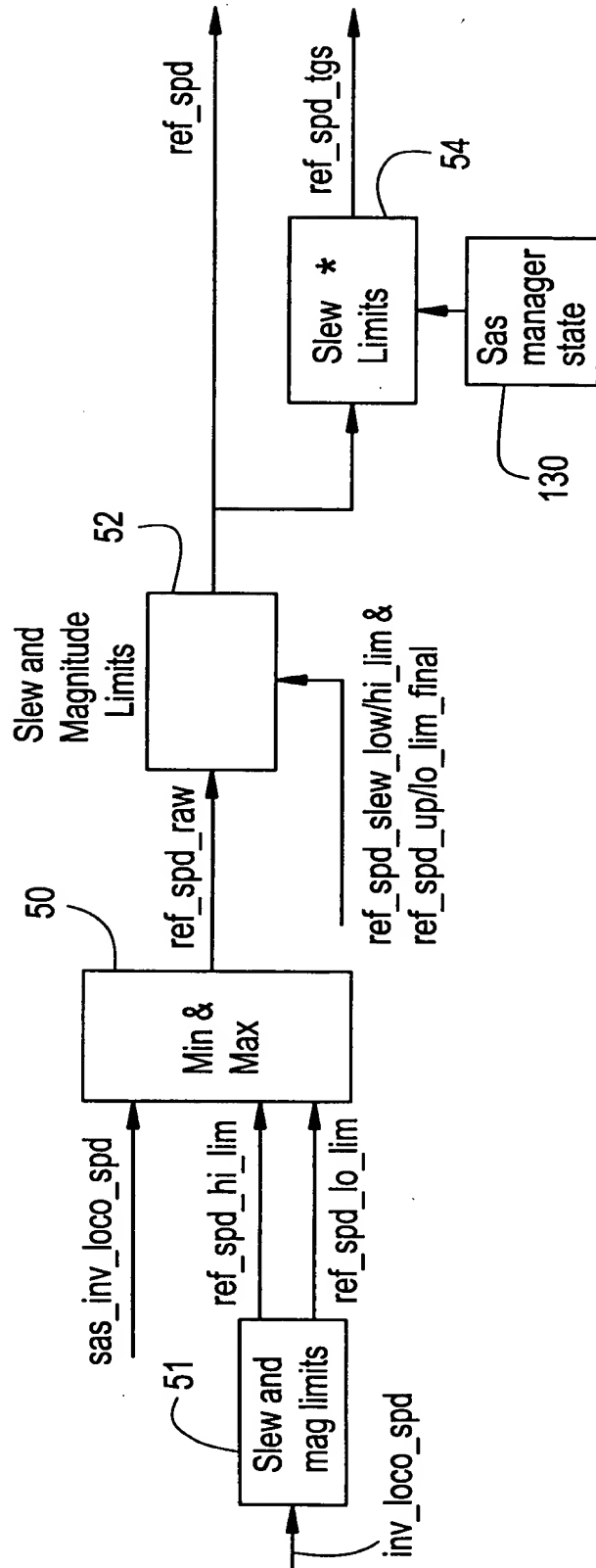


FIG. 2B



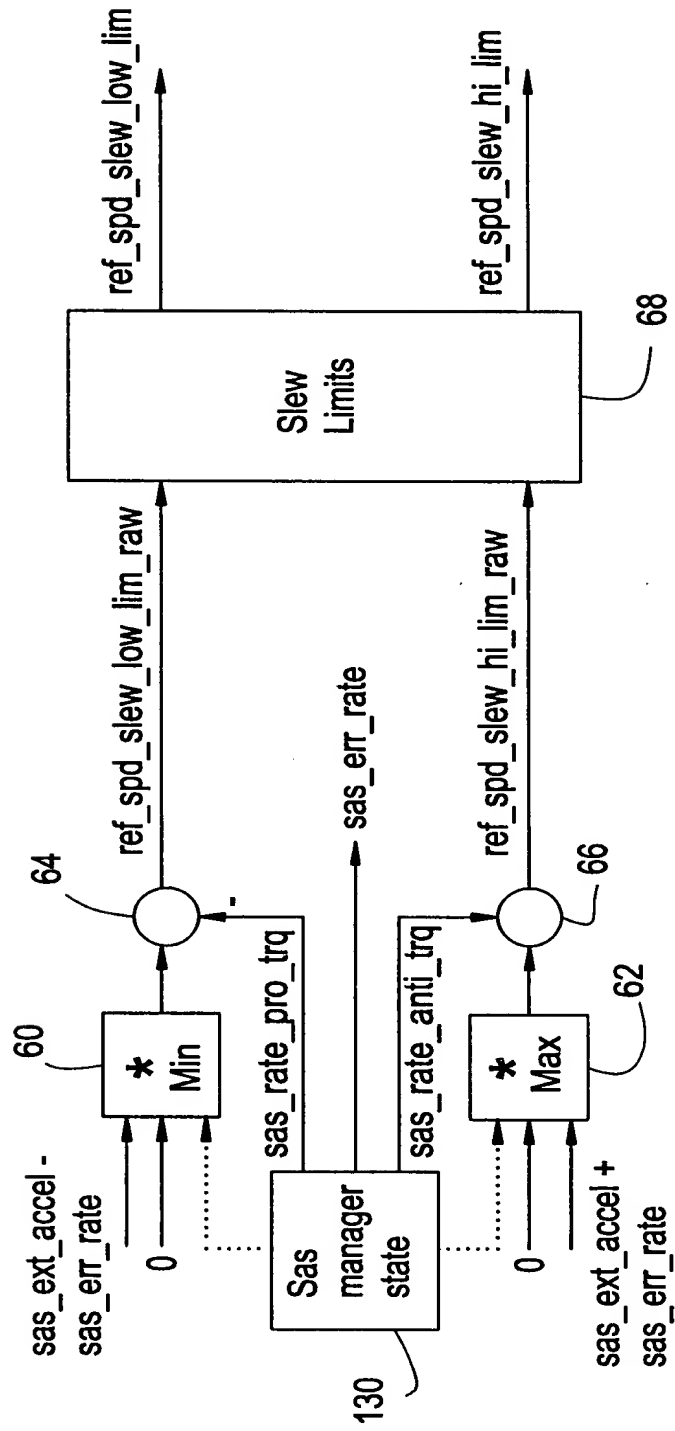
* Min if motoring &
Max if Braking

FIG. 2C



* no limits wide or narrow
 else tight limits for synchronous
 slip protection

FIG. 2D



* set output to 0 if not wide or narrow

FIG. 3

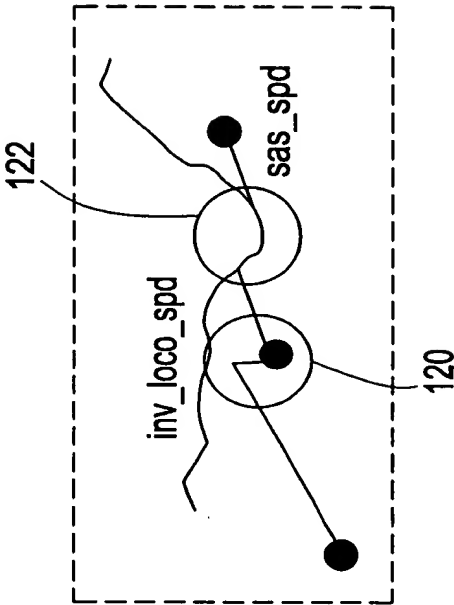
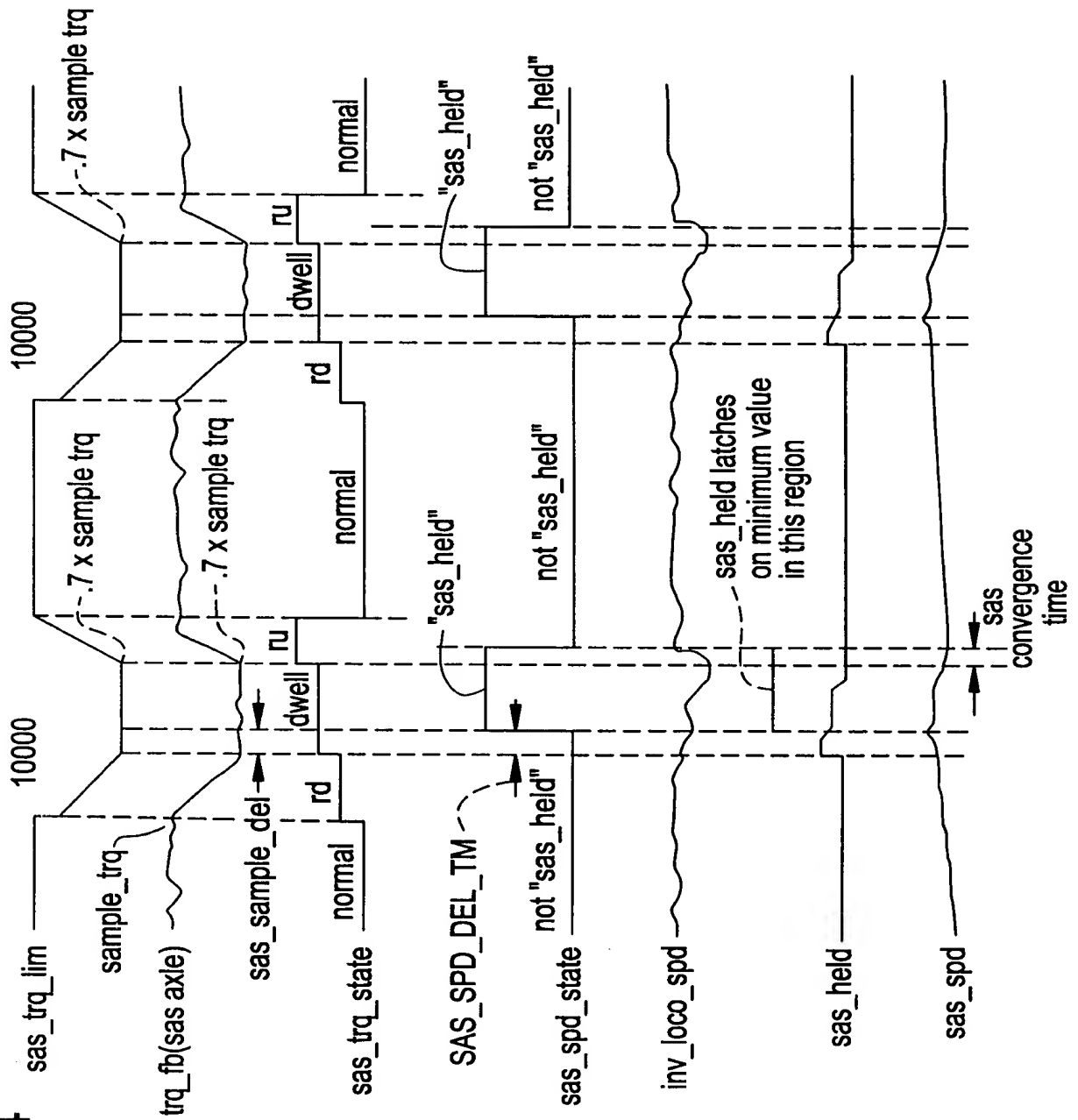


FIG. 4



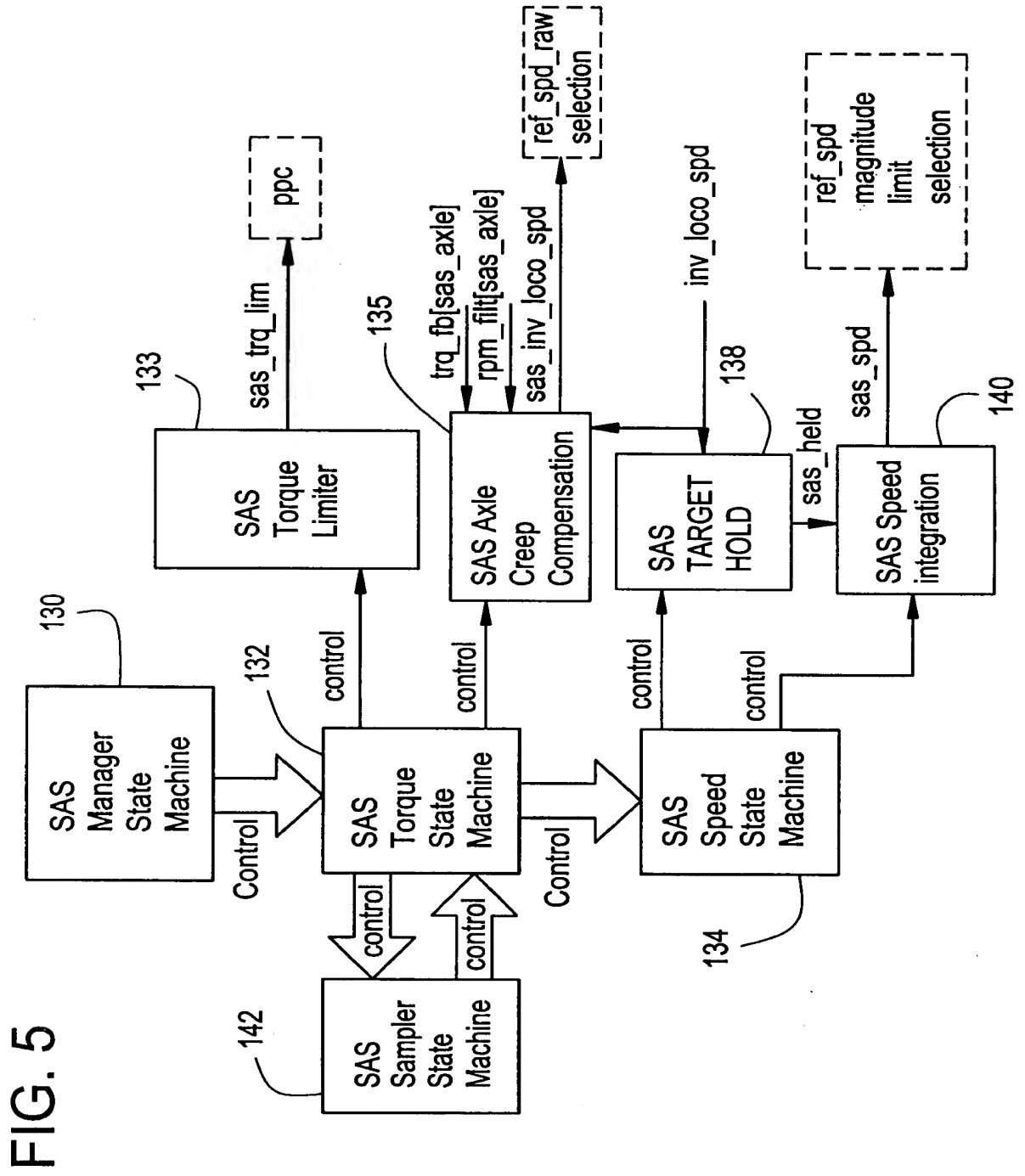
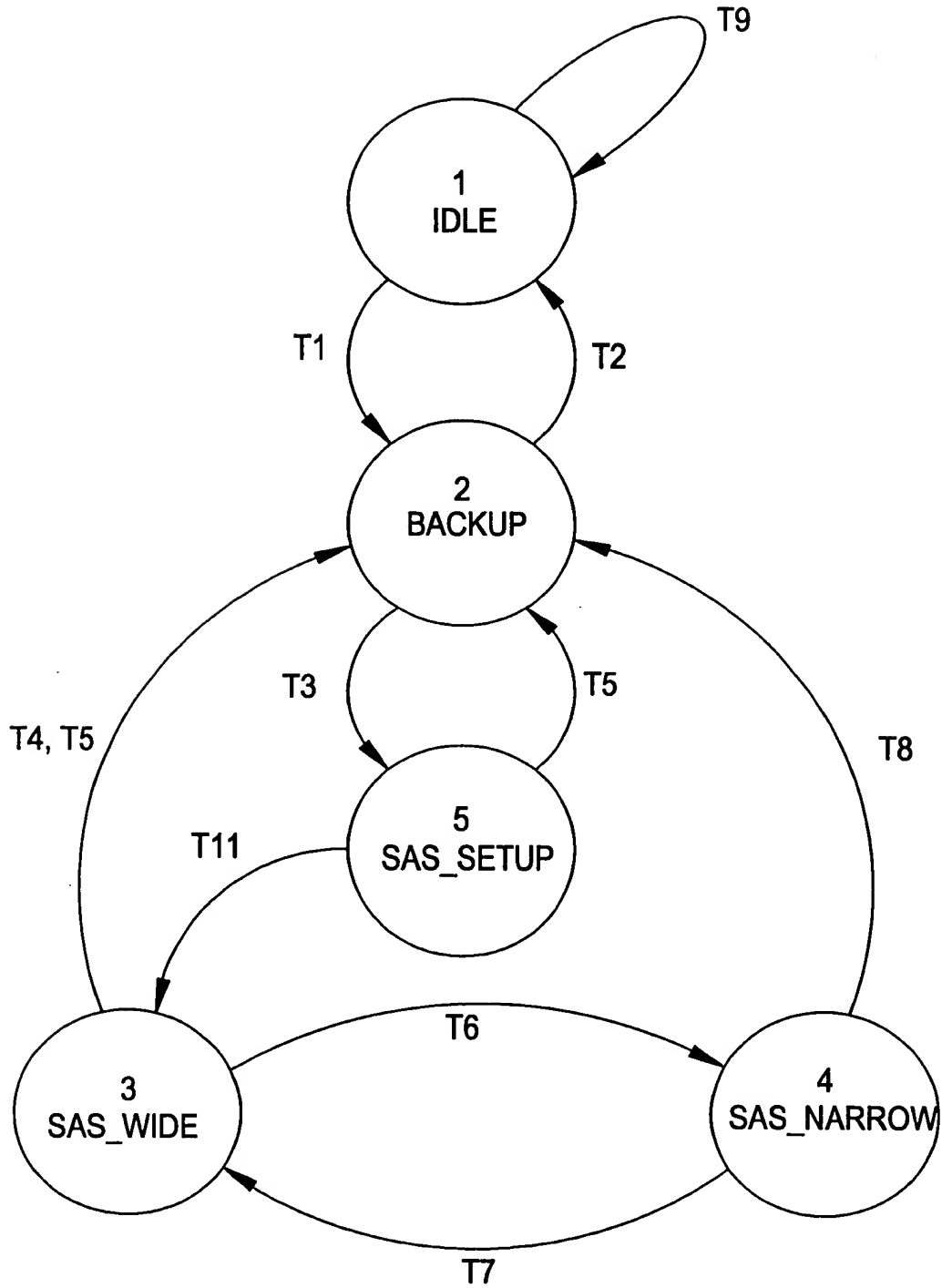


FIG. 6



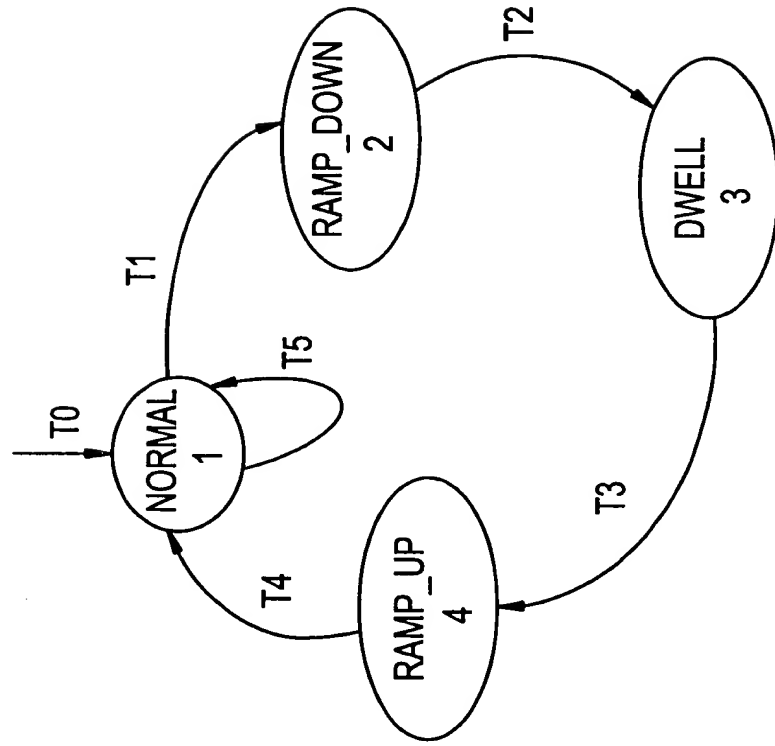


FIG. 7

FIG. 8

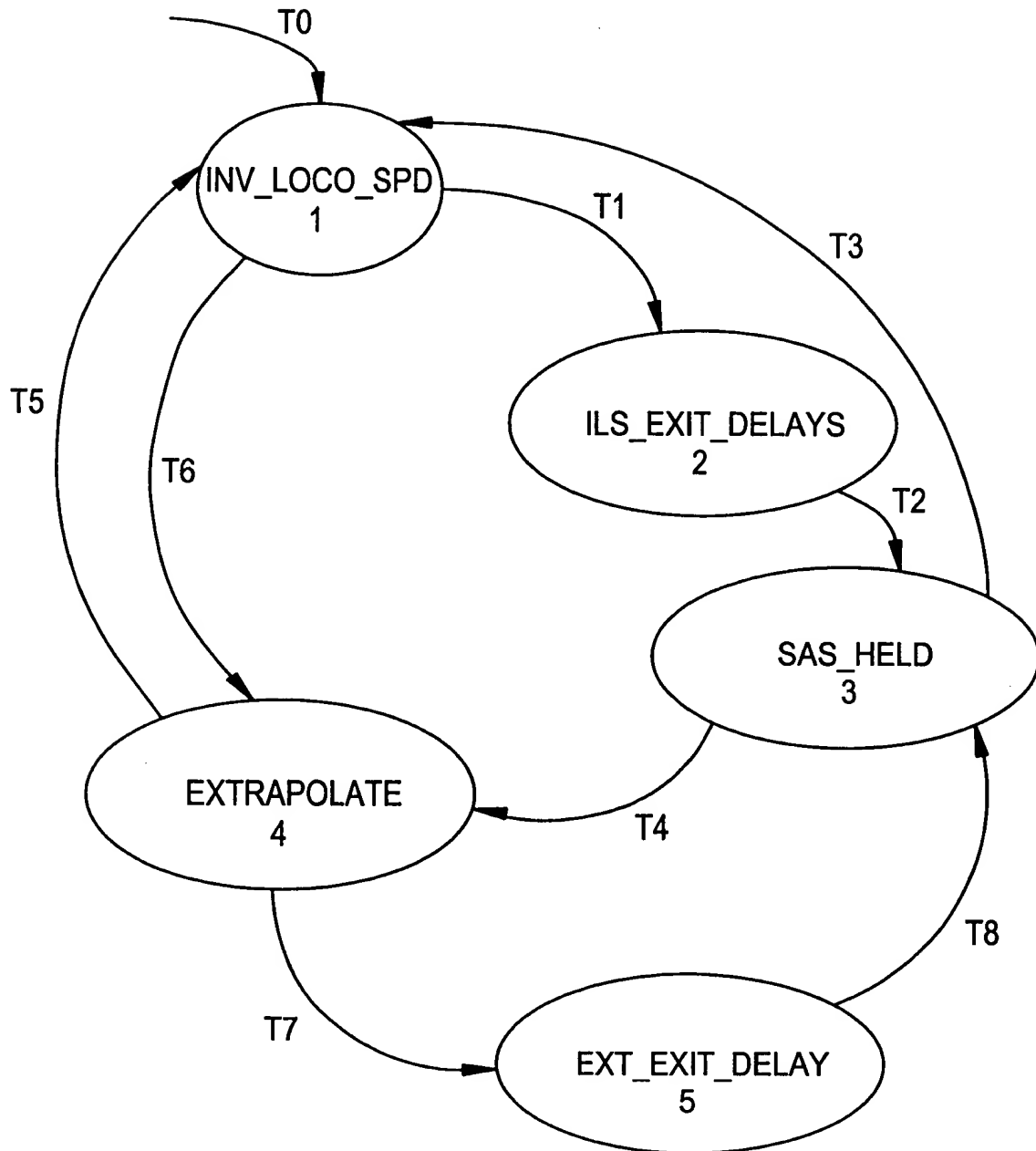


FIG. 9

